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🌐 <https://ihsan149.github.io>

🌐 <https://sites.google.com/view/mispl/home>



Research Statement

Most deep learning-based methods require a considerable amount of labeled data, which is difficult to come by in the computer vision and medical field. I am interested in developing a unsupervised domain adaptation methods to learn from synthetic data to mitigate the labeling efforts.

Keywords: Deep learning, Unsupervised Domain Adaptation, Segmentation, Classification, Detection.

Employment History

- 2018-03 – 2023-02 ■ **PhD Research Student**, MISPL, Robotics and Mechatronics Engineering, DGIST.
- 2017-09 – 2018-02 ■ **Post MS Researcher**, MISPL, Robotics and Mechatronics Engineering, DGIST.
- 2015 – 2017-08 ■ **MS Research Student**, Software Engineering Lab, Chonbuk National University .

Education

- 2018 – 2023 ■ **Ph.D. Robotics and Mechatronics Engineering** Daegu Gyeongbuk Institute of Science and Technology.
Thesis title: *Catheter Localization and Tracking using Convolutional Neural Networks with Generative Modeling.*
- 2015 – 2017 ■ **M.S. Computer Science and Engineering**, Chonbuk National University.
Thesis title: *Vehicles Information Extraction Based on Deep Neural Network.*
- 2010 – 2014 ■ **B.S. Computer Science**, Abdul Wali Khan University Mardan.
Thesis title: *Developed Dynamic Website (Crime File Management System).*

Research Publications

Articles in Submission/Preparation

- 1 **Ullah, I.**, An, S., Myeong Kyun, K., & Park, S. H. (In Review). Video domain adaptation for semantic segmentation using perceptual consistency matching. In *Computer vision and pattern recognition*. CVPR23.
- 2 **Ullah, I.**, Baber, S., Ali, F., El-Sappagh, S., Abuhmed, T., & Park, S. H. (Fourth round revision). A deep learning based dual encoder-decoder framework for anatomical structure segmentation in chest fluoroscopic images. In *Scientific reports*. Elsevier.

Journal Articles

- 1 Farman, A., Muhammad, S., Tariq, H. S. B., **Ullah, I.**, Sayyed Mudassar, S., & Park, S. H. (Accepted). Deep learning-based segmentation and classification of leaf images for detection of tomato plant disease. *Frontiers in Plant Science*. Retrieved from <https://www.frontiersin.org/articles/10.3389/fpls.2022.1031748/abstract>
- 2 Jeong, J., Hong, S. T., **Ullah, I.**, Kim, E. S., & Park, S. H. (2022). Classification of the confocal microscopy images of colorectal tumor and inflammatory colitis mucosa tissue using deep learning. *Diagnostics*, 12(2), 288. [doi:10.3390/diagnostics12020288](https://doi.org/10.3390/diagnostics12020288)

- 3 **Ullah, I.**, Chikontwe, P., Choi, H., Yoon, C.-H., & Park, S. H. (2021). Synthesize and segment: Towards improved catheter segmentation via adversarial augmentation. *Applied Sciences*, *11*(4), 1638. [doi:10.3390/app11041638](https://doi.org/10.3390/app11041638)
- 4 Allan, M., Kondo, S., **Ullah, I.**, Bodenstedt, S., Leger, S., Kadkhodamohammadi, R., ... Pedersen, M. et al. (2020). 2018 robotic scene segmentation challenge. *arXiv preprint arXiv:2001.11190*. Retrieved from <https://arxiv.org/abs/2001.11190v3>
- 5 Lee, H. J., **Ullah, I.**, Wan, W., Gao, Y., & Fang, Z. (2019). Real-time vehicle make and model recognition with the residual squeezeNet architecture. *Sensors*, *19*(5), 982. [doi:10.3390/s19050982](https://doi.org/10.3390/s19050982)
- 6 **Ullah, I.**, Chikontwe, P., & Park, S. H. (2019c). Real-time tracking of guidewire robot tips using deep convolutional neural networks on successive localized frames. *IEEE Access*, *7*, 159743–159753. [doi:10.1109/ACCESS.2019.2950263](https://doi.org/10.1109/ACCESS.2019.2950263)

Conference Proceedings

- 1 Chikontwe, P., **Ullah, I.**, Kim, J., Won, D., & Park, S. H. (2019). Recurrent attention models for tissue histopathology image classification. Retrieved from <http://ipiu.or.kr/2019/oral.html>
- 2 **Ullah, I.**, Chikontwe, P., & Park, S. H. (2019a). Catheter synthesis in x-ray fluoroscopy with generative adversarial networks. In *"MICCAI PRIME", workshop* (pp. 125–133). Springer. Retrieved from https://link.springer.com/chapter/10.1007/978-3-030-32281-6_13
- 3 **Ullah, I.**, Chikontwe, P., & Park, S. H. (2019b). Guidewire tip tracking using u-net with shape and motion constraints. In *2019 international conference on artificial intelligence in information and communication (ICAIIIC)* (pp. 215–217). [doi:10.1109/ICAIIIC.2019.8669088](https://doi.org/10.1109/ICAIIIC.2019.8669088)
- 4 Alam, M. N., **Ullah, I.**, & Al-Absi, A. A. (2018). Deep learning-based apple defect detection with residual squeezeNet. In *International conference on smart computing and cyber security: Strategic foresight, security challenges and innovation* (pp. 127–134). Springer. Retrieved from https://link.springer.com/chapter/10.1007/978-981-15-7990-5_12
- 5 **Ullah, I.**, & Lee, H. J. (2017). Moving vehicle detection and information extraction based on deep neural network. In *Proceedings of the international conference on image processing, computer vision, and pattern recognition (IPCV)* (pp. 102–107). The Steering Committee of The World Congress in Computer Science, Computer ... Retrieved from <https://csce.ucmss.com/books/LFS/CSREA2017/IPC6015.pdf>
- 6 **Ullah, I.**, & Lee, H. J. (2016a). An approach of locating korean vehicle license plate based on mathematical morphology and geometrical features. In *2016 international conference on computational science and computational intelligence (csci)* (pp. 836–840). IEEE. Retrieved from <https://ieeexplore.ieee.org/stamp/stamp.jsp?arnumber=7881455>
- 7 **Ullah, I.**, & Lee, H. J. (2016b). An effective algorithm for shadow removal from moving vehicles. In *International symposium on information technology convergence (ISITC 2016), shanghai china*. Retrieved from https://www.researchgate.net/publication/317184010_An_Effective_Algorithm_for_Shadow_Removal_from_Moving_Vehicles_Based_on_Morphology
- 8 **Ullah, I.**, & Lee, H. J. (2016c). License plate detection based on rectangular features and multilevel thresholding. In *Proceedings of the international conference on image processing, computer vision, and pattern recognition (IPCV)* (p. 153). The Steering Committee of The World Congress in Computer Science, Computer ... Retrieved from <http://worldcomp-proceedings.com/proc/p2016/IPC4045.pdf>
- 9 **Ullah, I.**, & Lee, H. J. (2016d). Moving object detection based on background subtraction. In *Conference of KIISE, june 29-july 01, 2016, jeju, south korea*. Retrieved from <https://www.dbpia.co.kr/pdf/pdfView.do?nodeId=NODE07017673>

Patents

1. Tracking of catheter tip using convolutional neural network

Title in Korean: 합성곱신경망을 이용한 카테터 끝단 추적기법

Inventors: **Ihsan Ullah**, DongKyu Won, Sang Hyun Park

Patent Number: 10-2174246

Application Number: 10-2018-0054790

Registration Date: 29/10/2020

Patent Link

2. Catheter Synthesis in X-Rays(Under-review)

Title in Korean: X-ray 카테터 시술 영상합성 기법

Inventors: **Ihsan Ullah**, Philip Chikontwe, Sang Hyun Park

Patent Number: 10-2174246

Filing Date: 2019-11-08

Application Number: P-2019-0256-KR-00

Projects Participation

- 2018 – 2022
- *Surgical robots segmentation and tracking in X-ray sequences based on deep learning.*
 - *Development of an augmented reality surgery system based on artificial intelligence for surgery.*
 - *Commercialization of immersive robot with multi-sensor technology.*
 - *Development and commercialization of micro/nano robot system for precise treatment of brain diseases and tumors.*
- 2015 – 2017
- *Vehicles Information Extraction Based on Deep Neural Network.*
 - *Face Recognition System Based on Deep Learning in Embedded System (Jetson TX1).*
 - *Deep Learning Based License Plate Detection.*

Skills

Languages	■ Strong reading, writing and speaking competencies for English. IELTS score 6/9 and TOEIC (710/990).
Coding	■ Python, C++.
Deep Learning Libraries	■ Tensorflow, Keras, PyTorch, Caffe.
Image Processing Libraries	■ OpenCV, DLib C++.
Web Dev	■ HTML, CSS, Apache Web Server.
Misc.	■ Academic research, teaching, training, consultation, \LaTeX typesetting and publishing.

Miscellaneous Experience



Presentations at Conferences, Symposia , Workshops, Seminar and Webinars

- 2022
- Presented a webinar on Catheter and Guidewire Segmentation via Adversarial Learning. in Pak-Austria Fachhochschule: Institute of Applied Sciences and Technology, Pakistan.
- 2019
- Poster presentation in IPIU Conference, Jeju, South Korea.
- 2018
- Poster presentation in Conference of KIISE, Jeju, South Korea.
- 2017
- Oral presentation in Information and Control Symposium, ICS'2017, Jeonju, South Korea.
- 2016
- Oral presentation in Conference of KISM and SEBS, April 29-30, 2016, Busan, South Korea.

Awards and Achievements

- 2018-2022
- **Scholarship Award**, DGIST Fully Funded Scholarship for PhD.

Miscellaneous Experience (continued)

- 2015-2017  **Scholarship Award**, Chonbuk National University, Fully Funded Scholarship for M.S.
  **Scholarship Award**, Chonbuk National University, Monthly Stipend from Brain Korea 21 Plus (BK-21 Plus).

Summer Schools

- 2019  **DGIST Summer School for Machine learning**. Awarded by DGIST.
2018  **DGIST Summer School for Medical Robot**. Awarded by DGIST.

Institutional and Professional Activities

-  Co-founder and member of DISA in DGIST.
-  Regional Coordinator Pakistani Student Association (PSAK) Korea in DGIST.
-  Active member of Pakistani Student Association (PSAK).

References

Prof. Sang Hyun Park, Ph.D

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